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Harkey

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(54) **FISHING ROD HOLDING APPARATUS AND METHOD**

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(58) **Field of Classification Search** 43/21.2, 43/25; 602/16, 21
See application file for complete search history.

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(57) **ABSTRACT**

A fishing rod holding apparatus which enables the fisherman to resist lateral and twisting loads imposed on the rod by a fish which is pulling the line from one side to the other. The apparatus comprises a forearm mounting section which is connected securely to the forearm, and a hand engagement section which engages the person's hand and also enables a gripping of the handle of the rod. The hand engagement apparatus is able to rotate about a side-to-side axis of rotation, but limits movement about a back-and-forth axis of rotation.

17 Claims, 4 Drawing Sheets

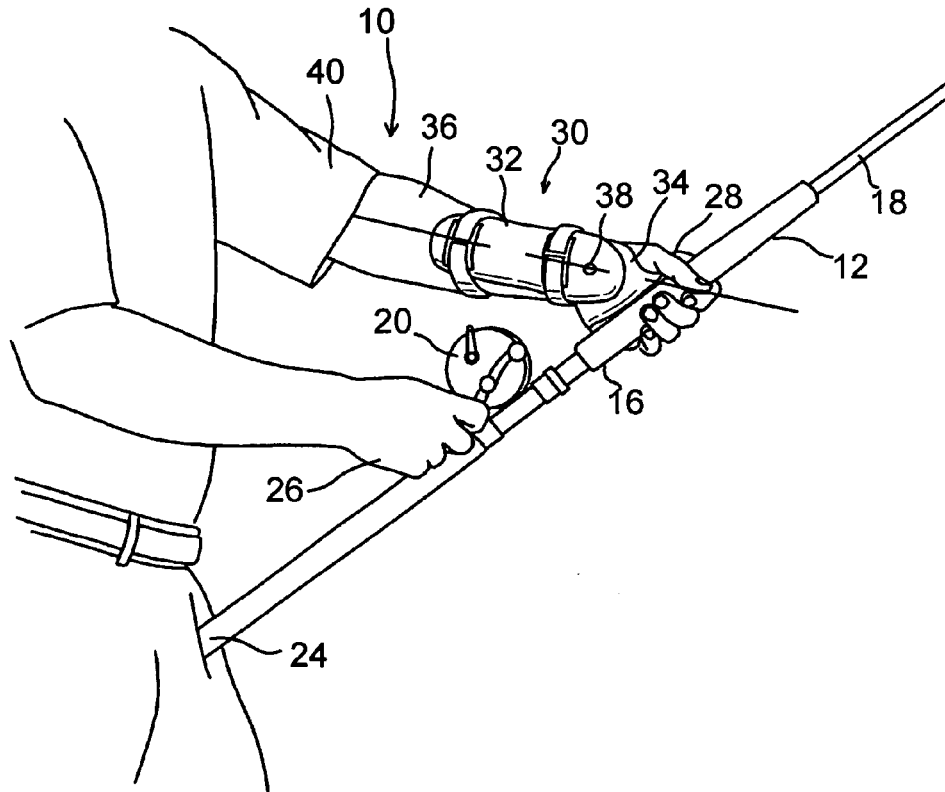


FIG. 1

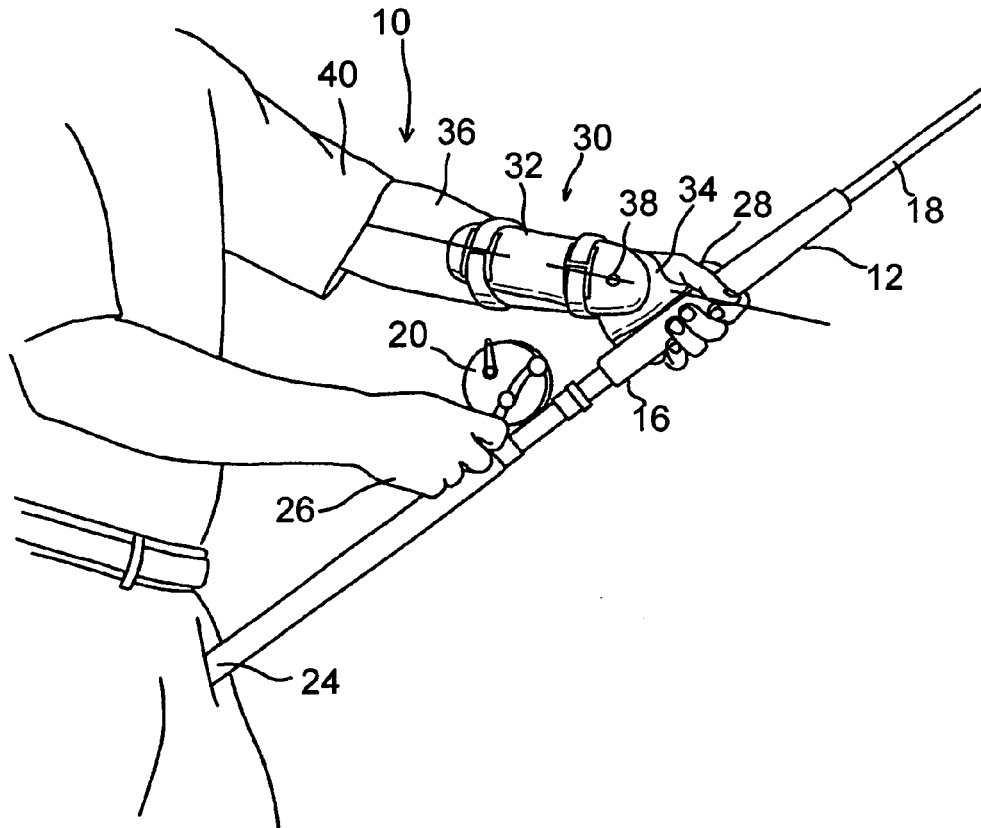
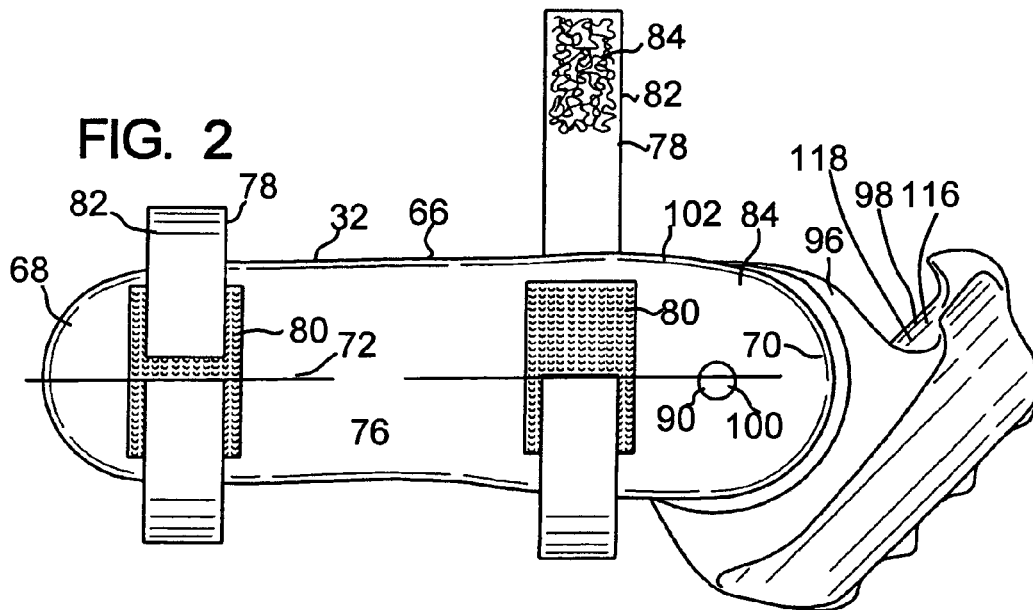


FIG. 2



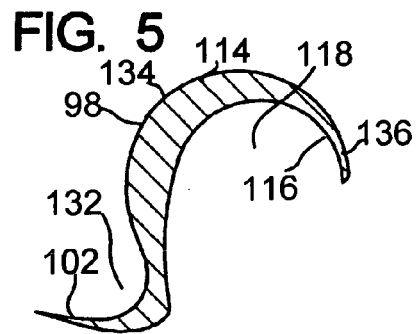
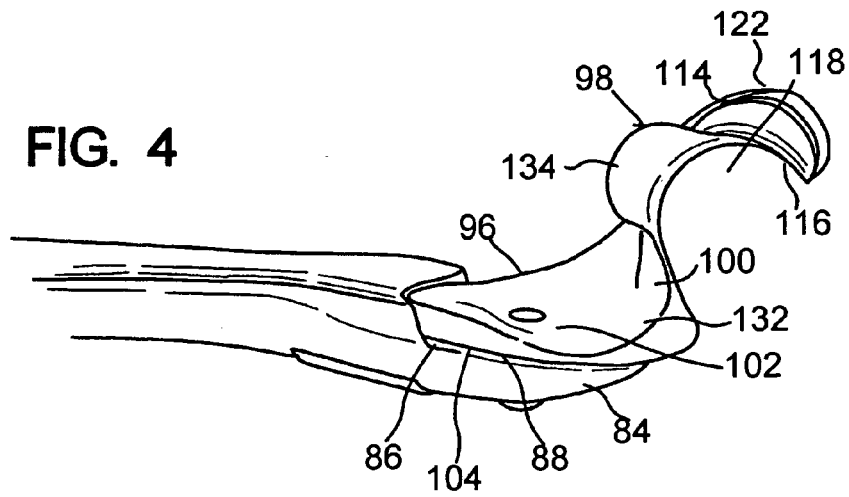
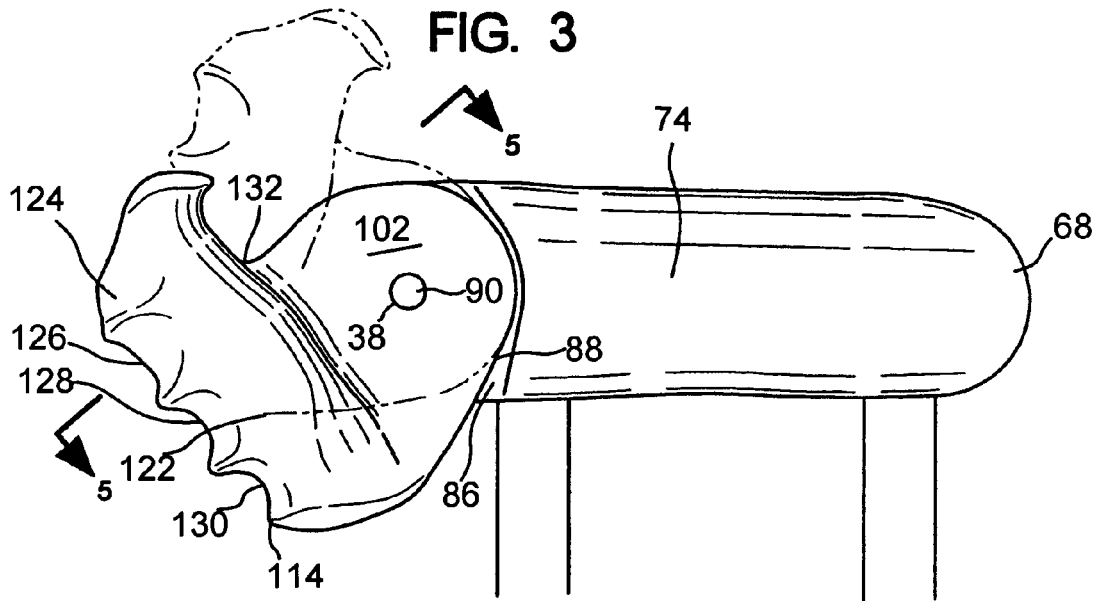


FIG. 6

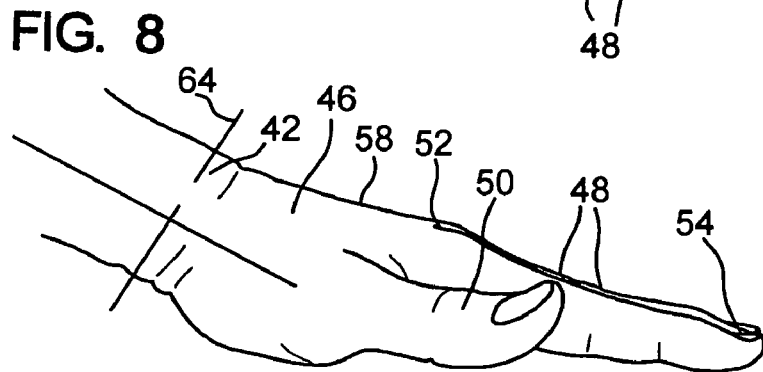
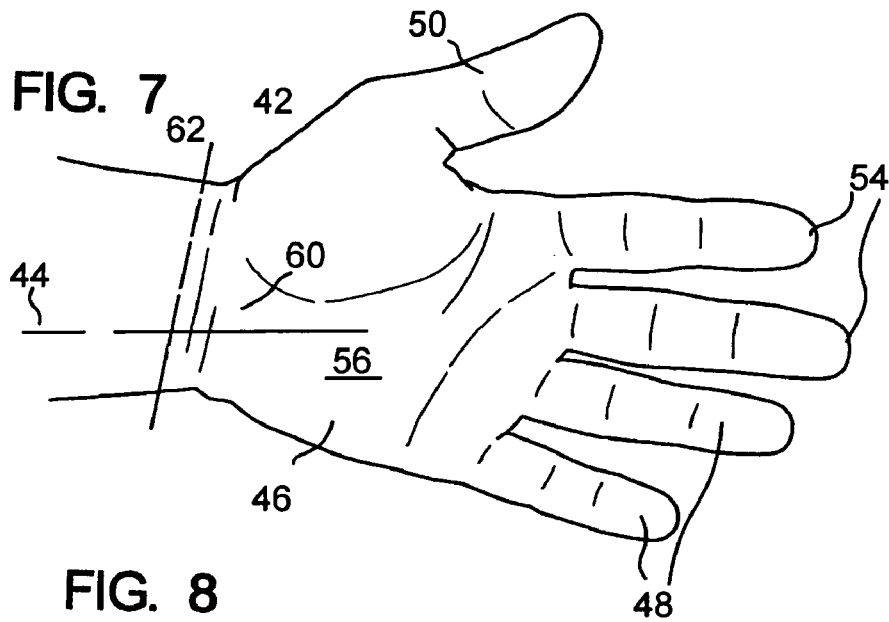
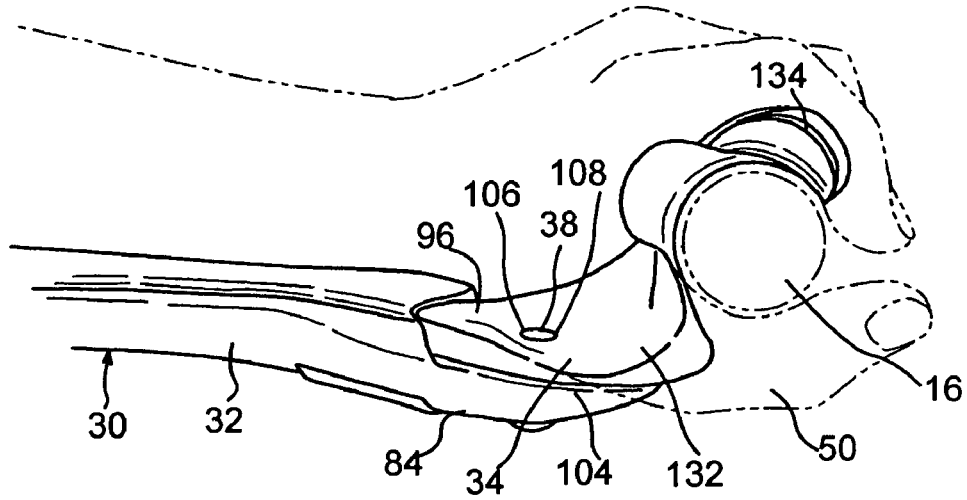


FIG. 9

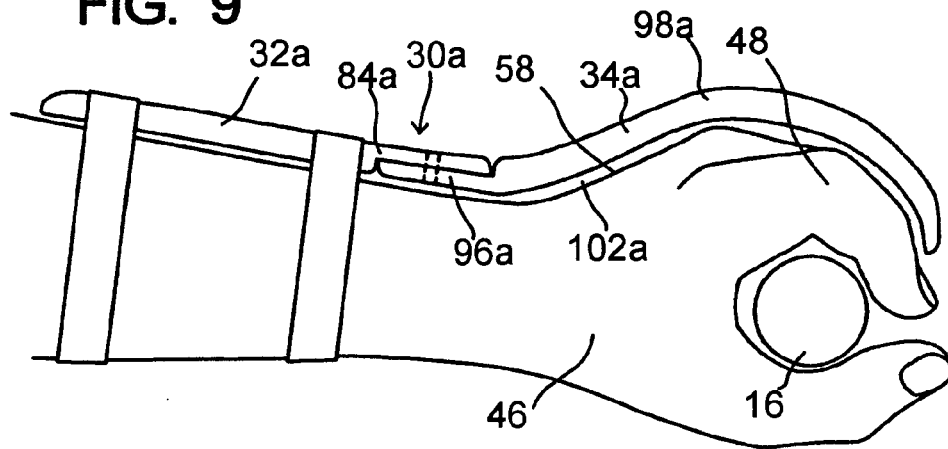


FIG. 10

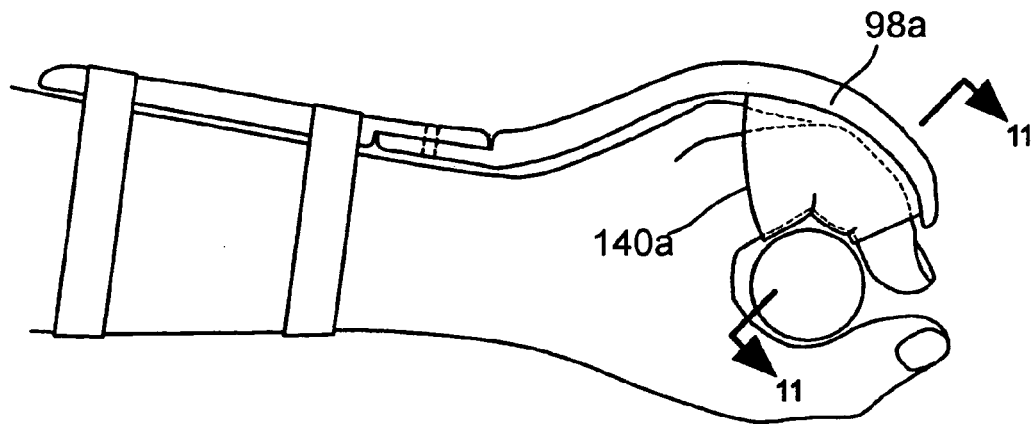
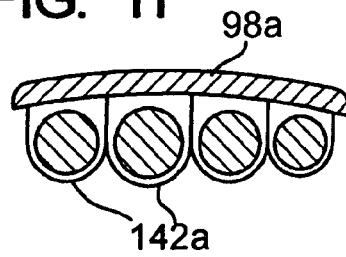


FIG. 11



FISHING ROD HOLDING APPARATUS AND METHOD

BACKGROUND OF THE INVENTION

1. Field of the Invention

The present invention relates to a hand grip apparatus and a method of using the same for better enabling a fisherman to effectively grip the fishing rod while alleviating the effect of some of the forces imposed on the rod in the performance in the task of landing the fish.

2. Background Art

When a fisherman is fishing for larger fish, a substantial amount of force from the pull of the line can be exerted at the tip end of the fishing rod to bend the rod in the direction of the pull. With regard to the stance that a fisherman will generally take when holding the fishing rod is that a right handed fisherman would commonly have his (her) left hand gripping the handle of the fishing rod at a more forward location and the fisherman's right hand would be operating the reel. The butt end of the rod would be braced against the fisherman's body, possible at the lower portion of the torso.

As the fish swims from side to side and further away and toward the fisherman, this will in some situations cause a force exerted in the fisherman's hand that is gripping the rod so that it will tend to cause a fisherman's wrist to twist from side to side as the fisherman is gripping the pole, and to rotate the pole in the person's hand. This can cause a certain amount of fatigue which would compromise the fisherman's ability to land the fish. The embodiment of the present invention is designed to alleviate this problem.

A search of the U.S. patent literature has disclosed a number of U.S. patents, some of these relating to assisting the fisherman, and some being in somewhat unrelated arts. These are as follows:

U.S. Pat. No. 6,564,389 B1 (Laughlin) shows a device to assist a person in lifting and manipulating a pot. A brace-like element **10** fits against the person's wrist. There is a forward end **12B** which has a U-shape and engages the handle **102** of the pot. This is also connected to a mitt **20** which has a forward mitt portion **20B** that fits around the person's hand.

U.S. Pat. No. 6,435,284 B1 (Aman) discloses a gardening tool where there is an upright handle **10** which is grasped by the person's hand, and there is a bracing member that engages the bottom of the handle and also fits over the person's wrist. There is a tool end portion, such as at the end of a hoe or several prongs that could dig into the soil.

U.S. Pat. No. 6,295,755 B1 (Macaluso) shows a fishing rod attachment that is secured to the butt end of the handle and has a support member **22** to engage the elbow. The person's hand (shown at **28**) grasps the rod.

U.S. Pat. No. 5,809,614 (Kretser, Jr.) shows a weed trimming device where there is a cradle or support that fits around the forearm and is held by Velcro or the like, and the forward end of this is clamped to the drive shaft assembly of a weed trimming device. The drive shaft assembly is shown at **60** in FIG. 6.

U.S. Pat. No. 5,716,087 (Backich et al.) shows a hand operated ergonomic scoop member that has a hand gripping portion **48**, and a rearwardly extending frame member **50** that engages the person's forearm to provide support.

U.S. Pat. No. 5,275,068 (Wrench) shows a device which relieves stress on the wrist joint when the person is manipulating, for example, a knife. The person's hand grasps a handle, and there is a forearm engaging member which

extends rearwardly from the knife along the fisherman's forearm, and which is strapped at its end closest to the elbow around the forearm.

U.S. Pat. No. 5,212,900 (Perry) shows what is called a "limb brace support device for fishing rods." There is an articulated brace which has an upper portion which engages the upper arm, and also a forearm portion engaging the forearm. Then, at the elbow joint there is a connection that can be made to the butt end **40** of a fishing pole. The person's hand at **46** grasps the fishing pole.

U.S. Pat. No. 5,159,775 (Sutula, Jr.) shows a support handle for a fishing rod where there is an arm clamp that extends along the fishing rod, and this also clamps to the person's forearm. The hand is positioned at the end of this member and grasps the fishing rod.

U.S. Pat. No. 3,367,056 (Johnson) shows what is called "cradle support extension for short casting rod," where there is a support arm member **13** engaging the fisherman's forearm and having a cradle member **14** at its upper end engaging the upper portion of the person's forearm. The person's arm is positioned so that the hand can grasp the handle of the fishing rod.

U.S. Pat. No. 3,372,510 (Arsenault) discloses a fishing rod handling device where there is a forward hand grip portion **28** extending upwardly from the length of the pole, and a rear arm support brace **34** which grasps the person's forearm **50**.

BRIEF DESCRIPTION OF THE DRAWINGS

FIG. 1 is a side elevational view showing a fisherman utilizing the apparatus of an embodiment of the present invention;

FIG. 2 is a side elevational view, with a portion thereof being drawn in an isometric fashion;

FIG. 3 is a elevational view similar to FIG. 2 except that it shows that the apparatus of this embodiment from the opposite side, and also with the hand engagement portion being shown in solid lines in one position, and broken lines in another position;

FIG. 4 is a isometric view that is taken perpendicular to the plain of the paper on which FIG. 3 is shown, and looking toward a thumb location of the embodiment;

FIG. 5 is a sectional view taken along line 5—5 of FIG. 3, but with this view being rotated from its cross section orientation in FIG. 3, so that it is at the same orientation as in FIG. 4;

FIG. 6 is a view similar to FIG. 4, but showing the fisherman's forearm and hand with the apparatus in its operating position, and also showing the fishing rod being gripped by the fisherman;

FIG. 7 is a view looking toward to palm of a fisherman's hand and lower forearm with the hand in an extended position generally parallel to the forearm;

FIG. 8 is a view similar to FIG. 7, but looking at the side of the fisherman's hand where the thumb is located;

FIG. 9 is a side elevational view similar to FIGS. 6, showing a second embodiment of the present invention in its operating position mounted to a person;

FIG. 10 is a side elevational view similar to FIG. 9, but showing a modified version of the apparatus; and

FIG. 11 is a sectional view taken along line 11—11 of FIG. 10.

DESCRIPTIONS OF THE EMBODIMENTS OF
THE INVENTION

As illustrated in FIG. 1, a fisherman will commonly grasp a fishing rod by having at least one hand gripping the fishing rod and another hand operating the reel. The butt end of the rod could be positioned, for example, against the fisherman's lower torso. If a larger fish is on the line, there can be substantial forces exerted in various directions, this resulting from the pull on the line, when the fish is swimming from side to side and towards and away from the boat or dock.

The pull that the fish exerts into the line is reacted at the tip end of the fishing rod and is transmitted into the handle portion. This will often result in a bending and/or twisting force exerted on the fisherman's hand that is gripping the rod. This can prove to be rather tiring and can compromise the ability of the fisherman properly landing the fish.

This embodiment of the present invention is directed toward alleviating this problem. The embodiment is an apparatus that comprises a forearm mounting section and a hand engagement section. The forearm mounting section in turn comprises a forearm engaging portion arranged to be connected in firm engagement with the forearm of the fisherman in an operating position, and a forearm interconnecting portion which, with the forearm engaging portion in its operating position, is located proximate to the wrist location.

The hand engagement section comprises a hand interconnecting portion and a rod connecting portion, and is arranged to be engaged by the fisherman's hand. The hand interconnecting portion and the forearm interconnecting portion are arranged to be connected to one another in a manner that in the operating position, the hand engagement section is able to rotate about a side to side apparatus axis of rotation which is coincident with, or proximate to, and substantially parallel to, a side to side hand axis of rotation about which a fisherman's hand rotates relative to the wrist. This is done in a manner that the hand engagement section is restrained from a rotational movement about an axis having a substantial alignment component perpendicular to said side to side apparatus axis of rotation. Thus, with apparatus in the operating position with the hand in engagement with the hand engagement section, the hand engagement section is restrained from movement that would cause any substantial rotational movement of the hand about a back and forth axis of rotation.

The rod engaging portion of the hand engagement section is arranged to engage a gripping location of the rod in a manner to retain the rod at least when the rod is subjected to a force directed to urge a backward rotation of the hand engagement section and react the force into the hand engagement section and into the forearm mounting section.

In this embodiment, the hand interconnecting portion has a main hand engagement surface portion which in the operating position comes into engagement with at least a portion of a surface of the main hand portion. In one arrangement the main hand engagement surface portion is located to engage at least a portion of the front palm surface of the hand.

To describe the embodiment in more detail, and with further reference to FIG. 1, there is shown a fisherman 10 who is holding an elongate fishing rod 12 having a longitudinal rod axis 14. The fishing rod 12 has a rear handle section 16 and a forward rod section 18. A reel 20 is mounted to the handle section 16 and there is a hand grip location 22 on the handle section 16.

The fisherman 10 is shown in a stance which would be typical in the situation where the fisherman is deep sea fishing, has landed a fish, and is in the middle of the task of landing the fish. The butt end 24 of the handle section 16 bears against the lower portion of the fisherman's torso (i.e. in the groin area as shown here), the right hand 26 of the fisherman is operating the reel 20 (either reeling in the fish, paying out line while placing a certain amount of drag on the line or neither of these), and the left hand 28 is located at the handgrip location 22 grasping the handle section 16.

The rod gripping apparatus 30 of this embodiment of the present invention is shown in its operating position in FIG. 1. The apparatus 30 comprises a forearm mounting section 32, and a hand engagement section 34. The forearm mounting section 32 is in firm engagement with the fisherman's left forearm 36, and the hand engagement section 30 is engaged by the fisherman's left hand 28. The two apparatus sections 32 and 34 are joined to one another for limited relative rotation about an operating axis of rotation 38, and this will be described in more detail later herein.

When the fisherman 10 is in the position shown in FIG. 10, with a fish on the line, the fish will commonly be swimming from side to side and thus will be imparting lateral/twisting loads into the front end of the fishing rod 12. These loads are in turn reacted into the fisherman's body by the butt end 24 of the handle section 16 that engages the fisherman's lower torso, and also into the fisherman's left hand 28 that is gripping the rod 12 at the gripping location 22 to extend both a lateral force and a twisting force (a force moment) that tends to rotate the handle about the longitudinal rod axis 14 of the fishing rod. As will be described more completely later herein, the rod gripping apparatus 30 of the present invention effectively alleviates some of the stress felt in the fisherman's hand and wrist because of such imposed loads, and yet better enables the fisherman to effectively grip and position the rod while rotating the hand to various side-to-side orientations in performing the task of eventually reeling in the fish.

It is believed that a better appreciation of structure and function of the embodiment of the present invention will be obtained by first discussing with reference to FIGS. 7 and 8 the anatomy of the fisherman's left forearm 36 and left hand 28 as it relates to the apparatus 30 of this embodiment of the present invention. Then this embodiment of the invention and its mode of operation will be described in more detail.

The left forearm 36 has a left elbow location which is identified and approximated by the numeral 40 in FIG. 1, and a wrist location 42 shown in 7 and 8. This forearm 36 also has a forearm alignment axis which is indicated at 44 in FIGS. 7 and 8 and extends from the elbow location 40 and through the center of the wrist location 42. In the following description this axis will be referred to as the longitudinal axis of orientation 44.

With reference to FIGS. 7 and 8, the fisherman's hand comprises the metacarpal portion of the hand (hereinafter for ease of expression being called the main hand portion 46), fingers 48, and a thumb 50. The fingers 48 connect to the main hand portion 46 at a finger connecting location 52 and the fingertips are indicated at 54. The main hand portion 46 has at the palm of the hand a front palm surface 56, and at the back of the hand a back hand surface 58. The heel 60 of the hand is at the base of the palm surface 56 near the wrist location 42.

To facilitate the description of the embodiment there will be established three axes of orientation, and reference is again made to FIGS. 7 and 8 which show the fisherman's left hand 28 and the forward part of the forearm 36, with the

fisherman's fingers **48** being in the extended position and the front surfaces of the fingers **48** being aligned in approximately the same plane as the plane occupied by the front palm surface **56**. There is the aforementioned longitudinal axis of orientation **44**, and a vertical axis of orientation **62** which passes through the longitudinal axis of orientation **44** at the wrist location **42** at a right angle to the longitudinal axis of orientation **44** and is nearly parallel to the plane occupied by the front palm surface **56** as shown in the position of FIG. **8**. (The term "vertical axis" is simply a term selected for convenience and does not relate necessarily to orientation relative to the earth's gravity.) A transverse axis of orientation **64** passes through the longitudinal axis **44** at the same location as does the vertical axis of orientation **62**, is perpendicular to both of the longitudinal axis of orientation **44** and the vertical axis of orientation **62**, and is approximately perpendicular to the front palm surface **56** in the position shown in FIGS. **7** and **8**.

In the this embodiment of the present invention, we will consider primarily two modes of rotational movement of the fisherman's hand **28** at the wrist location **42** relative to the forearm **36**. One mode of rotational movement will be considered as the "back and forth movement", and the second mode is the "side to side movement". The back and forth rotational movement will be considered as rotational movement about a "back and forth axis of rotation" which is coincident with the vertical axis of orientation **62**. Thus, the back and forth movement about the back and forth axis of rotation occurs where the movement of the hand **28** is such that the front palm surface **56** of the hand moves in a direction that is perpendicular to the front palm surface **56** of the hand **28**.

Then the "side to side" rotational movement occurs when the hand **28** is being rotated about the transverse axis of orientation **64**. Thus, when the fisherman is rotating the hand **28** at the wrist location **42** in the side to side rotational movement, with the hand extended and parallel with the longitudinal axis **44**, the palm surface **56** of the hand is moving in a plane parallel to the orientation of the palm surface **56**.

Thus, in the text which follows, the back and forth movement of the hand **28** will be considered to be about a "back and forth" axis of rotation that coincides with the vertical axis of orientation **62** will be given the same numerical designation **62**. In like manner, since the side to side movement of the hand will be considered to be about a side to side axis of rotation that is coincides with the transverse axis **64**, the side to side axis of rotation shall be given the same numerical designation **64**.

With the foregoing text being given as background information, let us now turn our attention to FIGS. **2** through **6** to describe this embodiment of the present invention in more detail.

The forearm mounting section **32** comprises a forearm engaging portion **66** which has a rearward end **68** and a forward end **70**, and which can be considered as having a rearward to front forearm alignment axis **72** that would be generally parallel to the longitudinal axis **40** of the forearm **36** when engaging the forearm in the operating position. The forearm engaging portion **66** has a concave inner forearm engaging surface **74** and a convex outer surface **76**. The inner surface **74** is contoured to generally match the contour of the fisherman's forearm at the location to which it is mounted, which in this embodiment is that portion of the forearm surface that is aligned with the palm surface **56** of the fisherman's hand **28**.

The forearm mounting section **32** is securely connected to the forearm by means of a pair of spaced Velcro strap connections **78**. There are spaced Velcro patches **80** that are connected at spaced locations on the convex outer surface **76**, and the straps **82** have end Velcro portions **84** that attach to the patch **78**.

The forearm mounting section **32** also comprises a forwardly positioned forearm interconnecting portion **84** by which the forearm engaging section **32** is pivotally connected to the hand engagement section **34**. This forearm interconnecting portion **84** can be considered as a forward extension of the forearm engaging portion **66** that has a more flattened configuration to better match the contour of the wrist location **42** of the fisherman's hand **28**. The inwardly facing surface portion of the forearm interconnecting portion **84** is formed with a shallow recess **86** having a contact surface **88** so as to be spaced a short distance away from the hand surface at the wrist location **42** of the fisherman when the apparatus **30** is in its operating position engaging the fisherman's forearm and hand.

At a central location in this contact surface **88**, there is a pivot location **90** which has a through opening to receive a pivot connecting pin. The recessed portion **86** has a curved edge portion **92** which, as will be described later herein, is proximate to an interconnecting portion of the hand engagement section **34**.

The hand engagement section **34** comprises a hand interconnecting portion **96** by which the hand engagement portion is pivotally connected to the interconnecting portion **84** of the forearm mounting section **32**, and a rod engaging portion **98** to engage the handle section **16** of the fishing rod **12**. Also, the hand interconnecting portion **96** and the rod engaging portion **98** can be considered as having a transition portion **100**.

The hand interconnecting portion **96** has a main hand engagement surface portion **102** which, with the apparatus **30** in its operating location bears against at least the heel portion of the fisherman's hand. The hand interconnecting portion also has a contact surface portion **104** that is on the opposite side of the hand interconnecting portion **96** relative to the main hand engagement surface portion **102** to engage the contact surface **88** of the forearm interconnecting portion **84**. The hand interconnecting portion **96** has a centrally located pivot location **106** which receives a connecting pivot pin **108**, which was mentioned previously herein as also extending through the opening at the pivot location **90** of the interconnecting portion **84** of the forearm mounting section **32**.

The axis of rotation defined by the pivot pin **108** is the same as the operating axis **38** that was mentioned earlier in this text. This operating axis of rotation **38** is located so that with the apparatus **30** in its operating position the axis of the rotation **38** that is defined by the pivot pin **108** is at, or proximate to, the side to side axis of the rotation **64** of the hand, and as will be described later herein, it restrains the motion of the hand engagement section **34** to rotational movement in a rotational side to side movement generally matching the side to side movement of the hand **28** with the apparatus **30** in its operating position. The contact surface **104** of the hand interconnecting portion **96** matches the contour of the contact surface **88** of the interconnecting portion **84** of the forearm engaging section **32** so that these surfaces **88** and **104** can rotate relative to one another as the hand engagement section **34** rotates relative to the forearm engaging section **32**. For example, both of these surfaces **88** and **104** can be made flat, or these could be made as matching conical surfaces.

The rod engaging portion **98** of the hand engagement portion **34** extends outwardly from the hand interconnecting portion **96** and is formed as a wall **114** which has a concavely curved inner surface **116** which defines an elongate laterally aligned recess **118** which in cross sectional configuration has an interior rounded surface that generally matches the circular configuration of the handle section **16** of the fishing rod **12**. This inner surface **116** is made with a high friction material such as a rubber or rubber like surface, to resist the rotational twisting of the axis of the rod handle **16** about the longitudinal rod axis **14** when the fisherman is gripping the handle **16**.

The curved wall of the **114** of the pole engaging portion **98** has an outer generally curved convex gripping surface **122** which is shaped to be gripped by the fingers of the **48** of the fisherman's left hand **28**. In the particular form shown herein, the gripping surface **122** is formed with finger receiving grooves **124**, **126**, **128**, and **130** which receive, respectively, the index finger, the middle finger, and the ring finger, and the little finger, and the little finger.

At a location adjacent to the index finger location, there is a side thumb recess **132** to accommodate the inner portion of the fisherman's thumb **50** and to permit the thumb **50** to be positioned around the fishing rod handle **16** when the handle is positioned in the handle receiving recess **116**, as shown in FIG. 6. Also, it will be seen in FIG. 6 that there is a raised portion **134** which is positioned as seen in FIG. 6, upwardly and somewhat forwardly of the thumb recess **132** to engage the fisherman's hand **28** at the location near the base of the index finger **124**.

To describe now the method of this embodiment, the fisherman **10** first positions the forearm mounting section **32** of the apparatus so that forearm engaging portion **66** is positioned against the forearm **36** with the alignment axis **72** forearm mounting section **32** being generally aligned with the longitudinal axis of orientation **44** of the forearm **36**. Then the Velcro straps **78**, positioned at forward and rearward locations on the forearm engaging portion **66** are strapped tightly around the forearm **36** and the forearm engaging portion **66** to hold the forearm engaging portion **66** firmly against the forearm **36**. The positioning of the forearm engaging portion **66** relative to its location along the longitudinal axis of orientation **44** of the forearm **36** is such that the pivot location **90** of the interconnecting portion **84** of the forearm engaging portion **34** is coincident with (or in proximity with) the side to side axis of rotation **64** of the left hand **28**. This places the hand gripping apparatus **30** in its proper operating position.

As shown in FIG. 1, the fisherman has the gripping apparatus **30** mounted to his left forearm **36**. This fisherman **10** as shown is right handed, so (as mentioned previously), in the normal mode of operation, the fisherman would have the rod mounted as shown in FIG. 1, with the left hand **28** gripping the hand engagement section **134** of the gripping apparatus **30** to in turn grip the rod handle **16** at the gripping location **22**, the right hand **26** being used to operate the reel **20**, and the butt end **24** of the handle **16** engaging the fisherman's lower torso, possibly in the groin area. Obviously, if the fisherman is left handed, then the same type of stance would be assumed by the fisherman **10** but in the configuration of a mirror image, shifting the left to the right, etc.

With the apparatus **30** in this operating position, the fisherman now grasps the fishing rod **12** and operates the fishing rod **12** in the customary manner when he (she) is fishing. Let us assume that the bait of the fisherman has now been taken by a fish and the fish is swimming in various

directions toward and away from the boat, from side to side, at greater or lesser depths etc. As this happens, the tension force on the fish line is pulling the outer end portion of the rod in various directions and at various slants relative to the horizontal. Let us assume that in the situation of FIG. 1, the fish is moving off to the left and pulling the outer end of the rod **12** toward the left. When this occurs, with the butt end **24** of the rod engaging the fisherman's body and thus being essentially stationary, the force exerted on the end of the rod tends to pull the gripping location **22** of the handle **16** to the left.

If the apparatus **30** were not used, this force would be pushing against the fisherman's left hand **28** to be pushed to the left, so that it would tend to rotate the hand **28** backwards relative to the wrist **42**, with this rotation taking place about the back and forth axis **62** of the fisherman's left hand **28**. Also, with the front end of the rod being deflected downwardly and pulled laterally there is a twisting force transmitted into the handle **16** to twist the handle **16** about the longitudinal rod axis **14** which in turn tends to twist the gripping hand **28** in a direction to tend to rotate the hand **28** about the back and both axis of rotation **62**. The repeated application of this force on the fisherman's left hand can eventually prove tiring, and the resulting fatigue can compromise the fisherman's physical ability to operate the rod **12** in an optimized manner.

However, with the apparatus of the present invention being mounted to the fisherman's left forearm **36**, the force that is exerted from the tip of the rod down to the hand gripping portion **22** of the handle **16** is now applied into the rod engaging portion **98** of the hand engagement section **32** to transmit this force through the interconnecting portions **84** and **96**, to the forearm engaging portion **66** into the forearm **36**. It is not possible, however, to rotate the hand engagement section **34** about a back and forth axis rotation since the contact surface **88** and the contact surface **104** remain in contact with one another and are held together by means of the connecting pivot pin **108**.

However, at the same time, rotation of the hand engagement section **34** about the side to side operating axis **38** is not restrained, and this mode of rotation is shown in FIG. 3. Thus the fisherman is able to maintain the same grip on the handle **16** as he is pulling the rod **18** up towards his body and more toward a vertical position, or lowering the rod **18** downwardly toward a more horizontal position, as shown in FIG. 1.

To explain another facet of the present invention, reference is made to FIG. 5. It can be seen that FIG. 5 is a sectional view taken along the lines 5—5 of FIG. 3, and it has in placed in an orientation which would correspond to FIG. 4.

It can be seen that the inter surface **116** that forms the recess **118** is in a nearly 180 degree curve so that it can snugly grip the handle grip portion **22** of the rod. The apparatus **30** can be made of plastic or some other material, and be molded into the shape as shown in FIG. 5 in the other drawings. In this particular configuration the outer most end finger portion **136** has a lesser thickness dimension than a middle portion of the rod engaging portion **98**. Thus, the fingertip portion **136** has a moderate amount of flexibility so that when the fingertip portion of the fisherman's fingers is gripping the outer end portion **136** of the rod engaging portion **98**, the fisherman is able to squeeze the outer portions of the fingers inwardly and have the feel of grasping the rod handle grip portion **122** as well as applying a gripping force to prevent rotation of the rod **12** about the longitudinal rod axis. In FIG. 5, only an edge portion of the

hand engagement surface portion **102** is shown, and it can be seen that from examining the section line at FIG. **5**, that this represents the tapering of the hand interconnecting portion **96** to a narrow edge.

A second embodiment of the present invention will now be described with reference to FIGS. **9–11**. Components of the second embodiment which are similar to, or correspond to, components of the first embodiment, will be given like numerical designations, with an “a” suffix distinguishing those of the second embodiment.

The apparatus **30a** of the this second embodiment comprises a forearm engaging section **32a** and a hand engagement section **34a**. The apparatus **30a** of the first embodiment differs from the first embodiment in that the forearm mounting section **32a** and the hand engagement **34a** are positioned on the forearm **36** and the hand **28**, respectively, at side locations opposite to the positions of the forearm mounting section **32** and hand engagement section **34** of the first embodiment. Thus, the hand engagement section **34a** is in engagement with the back surface **58** of the main hand portion **46**, and the forearm mounting section **32a** is positioned on the side surface of the forearm **36** that is in alignment with the back surface portion **58** of the fisherman’s main hand portion **46**.

The forearm mounting section **30a** has generally the same configuration as the forearm mounting section **30** of the first embodiment, except possibly for the contouring of the inside contact surface of the forearm mounting section **32a** to conform more closely to the contours of that surface portion of the person’s forearm **36**. In like manner, the main hand engagement surface portion **102a** of the hand engagement section **34a** has a contact surface contour which matches the configuration of the back surface **58** of the fisherman’s hand.

In the first embodiment the forward part of the hand engagement section **34** comprises a forward end portion that is designated as a rod engagement portion **98** that has a transition portion **100** connecting to the hand interconnecting portion **96**. This second embodiment differs from the first embodiment in that the forward portion **98a** of the hand engagement section **34a** does not function directly as a rod engaging portion such as indicated at **98** in the description of the first embodiment. Rather, the forward portion of the hand engagement section **34** functions as a finger positioning and support function for the person’s fingers **48** to enable the fingers **48** themselves to engage the rear handle section **16** of the rod **12**, and only indirectly engages the rod handle **16** in the operating position. Thus, this forward hand engagement portion **98a** of the second embodiment has a contour matching the back surfaces of the fingers **48** when these fingers **48** are in the gripping position, as shown in FIGS. **9** and **10**, grasping the rod handle **16**.

The forward interconnecting portion **84a** of the forearm section **32a** and the hand interconnecting portion **96a** of the hand engagement section **38a** function basically in substantially the same way as the corresponding components **84** and **96** of the first embodiment by providing for a limited relative rotation around a pivot location **90a** which corresponds to pivot location **90** of the first embodiment. Thus, the side to side motion of the person’s hand is permitted while the back and forth motion of the hand is restrained by the hand engagement section **34**.

In the operation of this second embodiment, the apparatus **30a** is mounted to the person’s forearm **36** as shown in FIGS. **9** and **10**, with the forearm mounting section **32a** being attached to the forearm **36** by the straps **78a** (in these embodiments Velcro straps) in a manner similar to the first embodiment. This automatically positions the hand engage-

ment section **34a** so that it is located adjacent to the back surface **58** of the main hand portion and also the back surface portion of the person’s fingers **48**. Thus the person grasps the rod handle **16** directly by the fingers engaging the rod handle **16**.

Thereafter, the fisherman operates the fishing rod **12** in the customary manner as described above. As the fish line is pulled in various directions by the fish, the person’s hand and fingers are supported by the hand engagement portion **34a** in the gripping position as shown in both FIGS. **9** and **10**. The fisherman grips the rod handle **16** with the person’s fingers **48** and thumb **50** pressing against the surface of the fishing rod handle **16**. The forward portion **98a** of the hand engagement section **34a** may in one configuration be to some extent be resilient and be positioned so that there is an initial biasing force provided by the forward hand engagement portion **98a** to assist the person in gripping the rod handle **16**.

It would be possible to provide an auxiliary fitting that would extend from the backside of the hand engagement section **34a** around or partly around the portion of the person’s hand at or closer to the front palm surface **56**, and partly extending to the region of the thumb **52**.

FIGS. **10** and **11** show substantially the same arrangement as in FIG. **9** except that the forward hand engaging portion **98a** is provided with a finger glove member **140a** that is attached to the adjacent surface of the hand engagement portion **98a** and extends outwardly there from to form separate finger engaging components **142a**. The surface of the finger glove member **140a** could be made of a high friction material so as to improve the grip of the person on the rod handle **16** to prevent rotational movement of the rod along the longitudinal axis of the pole **12**. Further, this glove member could be extended rearwardly to engage the palm of the person’s hand so as to maintain the person’s hand in engagement with the hand engagement section **34a**.

Thus, the overall operation the second embodiment of the present invention is substantially similar to the first embodiment in its basic function of permitting the maneuverability of the person’s hand gripping the rod in the side to side motion which usually occurs when the fisherman is pulling the rod **12** back toward the fisherman or letting the rod move outwardly and downwardly from the fisherman. Yet the back force component and also the twisting force components that are imposed on the person’s hand by the action of the fish pulling on the line and moving from one side to the other are resisted to assist the person in reliably and maneuvering the rod **12** gripping the rod handle **16**.

It is obvious that various modifications could be made to the embodiments of the present invention. For example, the forearm engaging portion **32** or **32a** could be modified in various ways to firmly engage the forearm **36**. Also, while the Velcro straps **78** and **78a** are used to connect the forearm engaging portion **66** to the forearm **36**, other fastening means and connectors could be used. Further, various modifications could be made to the hand engagement section **34** and **34a** as well as to enter connecting portions **84**, **96**, **84a** and **96a**, since there are various ways of connecting two members together to rotate about a single axis of rotation.

I claim:

1. A combination fishing rod and gripping apparatus to assist a fisherman in gripping a handle of the fishing rod, with said fisherman having a forearm which has a longitudinal forearm axis of orientation, a rear elbow location and a rod gripping hand connected thereto at a wrist location, and with the hand having at the wrist location a side to side hand axis of rotation and a back and forth hand axis of

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rotation, and with the hand comprising a main hand portion with a front palm surface and a back surface and comprising a finger portion that has a base connecting finger location and an outer finger portion, said combination comprising:

- a) a fishing rod comprising a rear handle section and a forward rod section, and having a longitudinal rod axis;
- b) a gripping apparatus having a rear to front apparatus alignment axis with said apparatus alignment axis generally aligned with the longitudinal axis of orientation when mounted in an operating position to said forearm;
- c) said apparatus comprising a forearm mounting section which comprises a forearm engaging portion arranged to be connected in engagement to the forearm in said operating position and a forearm interconnecting portion which, with the forearm engaging portion in the operating position, is located proximate to the wrist location;
- d) said apparatus further comprising a hand engagement section which comprises a hand interconnecting portion and a forward hand engaging portion, and which is arranged to be engaged by the hand in an operation position;
- e) said hand interconnecting portion and said forearm interconnecting portion being arranged to be connected to one another in a manner that in the operating position the hand engagement section is able to rotate about a side to side apparatus axis of rotation which is coincident with, or proximate to, and substantially parallel to, the side to side hand axis of rotation, and the hand engagement section is restrained from rotational movement about a second axis having a substantial alignment component perpendicular to said side to side apparatus axis of rotation, in a manner that in the operating position with the hand of the person in engagement with the hand engagement section, the hand and the hand engagement section are limited in movement about said back and forth hand axis of rotation;
- f) said forward hand engaging portion of said hand engagement section comprising a hand engaging member having a concavely shaped inner surface having at least front and rear surface portions defining a laterally aligned, laterally facing recess that has oppositely positioned end openings and a laterally facing recess opening so that the rod can be moved laterally through the recess opening into the recess with the rod extending through end openings, and the rod can be moved laterally from the recess;
- g) said hand engagement section being arranged so that with the hand being engaged with the hand engaging portion in the operating position, the fingers of the hand are in engagement with the forward hand engaging portion, and the thumb of the hand is able to be positioned in a retaining position across the recess opening, and then with the thumb being moved to a release position away from the recess opening the rod can be moved through the release opening and out of the recess; and
- h) said combination being arranged so that with the forearm mounting section being connected in engagement with the forearm, with the hand in engagement with the hand engagement section in its operating position, and with the rod being in the operating position in the hand engagement section, the person's hand is able to exert a force on the rod while rotating the hand engagement section about the side to side axis,

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while reacting forces that would cause rotation about the back and forth axis into the gripping apparatus so as to reduce the effect of these forces on the person's hand and forearm.

2. The combination as recited in claim 1, wherein said hand interconnecting portion has a main hand engagement surface portion which in the operating position comes into engagement with at least a portion of a surface of the main hand portion.

3. The combination as recited in claim 2, wherein said main hand engagement surface portion is located to engage at least a portion of the front palm surface of the hand.

4. The combination as recited in claim 2, wherein said main hand engagement surface portion is located to engage at least a portion of the back surface of the hand.

5. The combination as recited in claim 2, wherein there is at said side to side apparatus axis of rotation a pivot member connecting said hand interconnecting portion with said forearm interconnecting portion.

6. The combination as recited in claim 2, wherein said hand interconnecting portion and said forearm interconnecting portion have contact surfaces arranged to limit relative movement between said hand interconnecting portion and said forearm interconnecting portion to rotational movement about said side to side apparatus axis of rotation.

7. The combination as recited in claim 1, wherein said hand interconnecting portion and said forearm interconnecting portion have contact surfaces arranged to limit relative movement between said hand interconnecting portion and said forearm interconnecting portion to rotational movement about said side to side apparatus axis of rotation.

8. The combination as recited in claim 2, wherein said forearm engaging portion has a forearm contact surface that forms with said main hand engagement surface portion a substantially longitudinally aligned contact surface.

9. The combination as recited in claim 1, wherein said forward hand engaging portion comprises a handle engaging portion having a hand gripping surface which in the operating position is positioned to be engaged at least in part by a front surface portion of the finger portion of the hand.

10. The combination as recited in claim 9, wherein said hand gripping surface is contoured to substantially match the front surface portion of the finger portion so as to be shaped in a contour of the hand in a rod gripping position.

11. The combination as recited in claim 9, wherein said rod engaging portion has a hand gripping surface which in the operating position is positioned to be engaged at least in part by a front surface portion of the finger portion of the hand.

12. The combination as recited in claim 11, wherein said hand gripping surface is contoured to substantially match the front surface portion of the finger portion so as to be shaped of the hand in a rod gripping position.

13. The combination as recited in claim 1, wherein said hand engagement section is formed with an open thumb accommodating region to receive a thumb of the hand in a manner that the thumb and can be positioned to enable the thumb to retain the rod in the receiving recess and can be moved laterally free of the hand engaging section.

14. The combination as recited in claim 1, wherein at least a portion of rod engaging portion that is engaged by said an outer finger portion of said finger portion of the hand has at least a moderate degree of flexibility so that a fisherman is able to apply a gripping force with the hand to squeeze said at least a portion of said rod engaging portion inwardly toward the fishing rod.

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15. The combination as recited in claim **1**, wherein said rod receiving recess is defined by a rod receiving surface made of a high friction material to resist a twisting rotational movement of the rod in the rod receiving recess.

16. The combination as recited in claim **1**, wherein said hand engagement section comprises a main hand engaging portion and a finger engaging portion, with said main hand engaging portion and said finger engaging portion engaging, respectively, a back surface of the main hand portion and a back surface of the hand finger portion, said finger engaging

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portion being contoured to engage the finger portion of the hand when in a gripping position.

17. The combination as recited in claim **16**, wherein said hand engagement section further comprises a glove portion positioned to be able to engage at least a finger portion of the person's hand with the hand being positioned adjacent to the hand engagement section.

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